



MATHÉMATIQUES  
VISION  
APPRENTISSAGE

# Riemannian Manifold Hamiltonian Monte Carlo

Samuel Bazaz, Mathis Hardion





# Plan

1. Context
2. Experiments
3. Conclusion

# HMC and RHMC : a better exploration!

## Geodesic flows

- Hamiltonian equations : modeling motion dynamics
- Hamiltonian = kinetic energy + potential energy
- RHMC: generalization with non-constant curvature

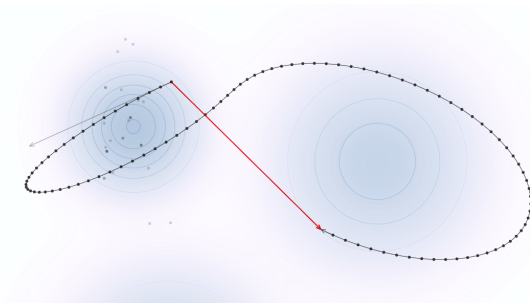


FIGURE 1: HMC from Chi Feng demo

## Questions raised by the document studied

### Girolami and Calderhead's paper areas of improvements [7]

- A better integration scheme ?
- A better metric ?
- A numerical estimation of the curvature?

### Theorem: two theoretical results

- Verlet's leapfrog is symplectic and assures time reversibility which implies detailed balance [4]
- The geodesic flow for negatively curved compact Riemannian manifolds is ergodic [1]

## Three improvements already made

### Three interesting papers

- Autodifferentiation for Bayesian neural network[6]
- No-U-Turn (NUTS) : The No-U-Turn Sampler [8]
- Softabs metrics[3] : " maintain the desirable behavior of the Hessian in convex neighborhood"

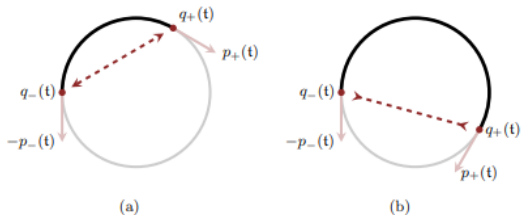


FIGURE 2: NUTS from 'A Conceptual Introduction to Hamiltonian Monte Carlo' [2]



# Plan

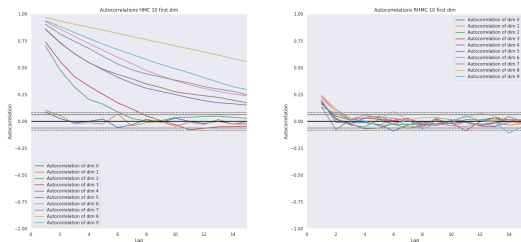
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# Automatic differentiation and HMC vs RHMC

## A trade-off between speed and precision

- Autodifferentiation makes RHMC slower and needs explicit solutions (x50 to x1000).
- Autocorrelations are far better for RHMC (no small oscillations).
- RHMC sampling has smaller KL divergence ( $0.3 < 1670$ )

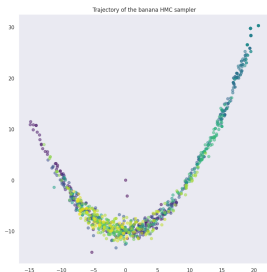
## HMC vs RHMC 200D Gaussian distribution



## More stable but needs better implementation

- Too slow to be used with implicate integration.
- Assure SDP stability.
- Should use a specialised framework, STAN ?

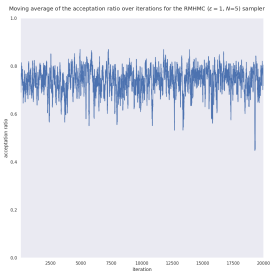
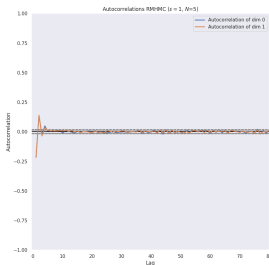
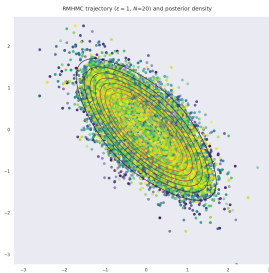
## HMC vs RHMC Softabs



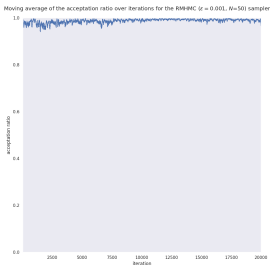
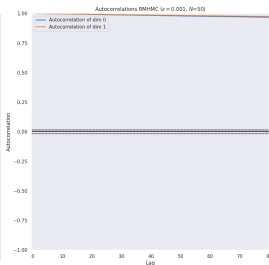
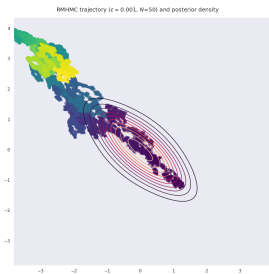


# Hyperparameter influences

$\epsilon = 1,$   
 $N = 5$

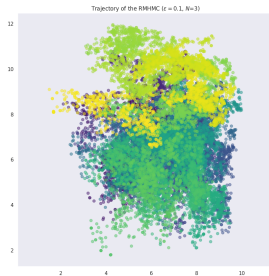
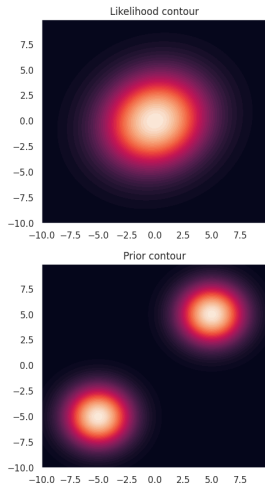


$\epsilon = 10^{-3},$   
 $N = 50$

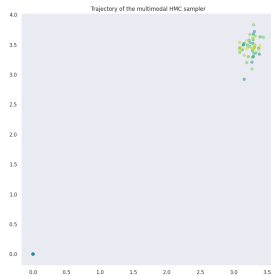


# Multimodal distributions for RHMC

## Gaussian mixture (RHMC)

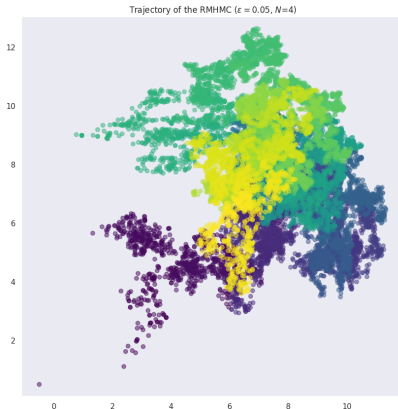


## HMC



## Adding the likelihood to the potential

- $\mathcal{L}(\theta) \rightarrow \mathcal{L}(\theta, Y) = \mathcal{L}(\theta) + \mathcal{L}(Y|\theta)$



- Does not help explore other modes in this case ...



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## Conclusion & extensions

- Easily implemented and can work really well, but hyperparameter tuning is not simple, done manually in the paper
- Derivation of the (expected) Rao metric is intractable in some cases (e.g. mixture models)
  - Approximation must be used or other metrics chosen
  - The problem of the right choice of matrix is not entirely solved although it gives very good directives
- Could be coupled with parallel tempering methods to better handle the multimodal case
- Alternative geometries could be investigated, for instance with MMD [5] or Wasserstein [9] distances

# References

- [1] D V Anosov. *Geodesic flows on closed Riemann manifolds with negative curvature*. Providence: American Mathematical Society Providence, 1969, iv, 235 pages 26 cm.
- [2] Michael Betancourt. *A Conceptual Introduction to Hamiltonian Monte Carlo*. 2018. arXiv: 1701.02434 [stat.ME].
- [3] Michael Betancourt. “A General Metric for Riemannian Manifold Hamiltonian Monte Carlo”. In: *Geometric Science of Information*. Springer Berlin Heidelberg, 2013, pp. 327–334.
- [4] Christopher M. Bishop. *Pattern Recognition and Machine Learning*. New York: Springer-Verlag, 2006, pp. 548–554.
- [5] Francois-Xavier Briol et al. *Statistical Inference for Generative Models with Maximum Mean Discrepancy*. 2019. arXiv: 1906.05944 [stat.ME].
- [6] Adam D Cobb and Brian Jalaian. “Scaling Hamiltonian Monte Carlo Inference for Bayesian Neural Networks with Symmetric Splitting”. In: *Uncertainty in Artificial Intelligence (2021)*.
- [7] Mark A. Girolami and Ben Calderhead. “Riemann manifold Langevin and Hamiltonian Monte Carlo methods”. In: *Journal of the Royal Statistical Society: Series B (Statistical Methodology)* 73 (2011).
- [8] Matthew D. Hoffman and Andrew Gelman. *The No-U-Turn Sampler: Adaptively Setting Path Lengths in Hamiltonian Monte Carlo*. 2011. arXiv: 1111.4246 [stat.CO].
- [9] Wuchen Li and Jiayi Zhao. *Wasserstein information matrix*. 2020. arXiv: 1910.11248 [math.ST].

# The curse of dimensionality

## Measure concentration

- Motivates Bayesian inference
  - Integration instead of Optimization
  - Monte Carlo estimation
- Motivates manifold hypothesis

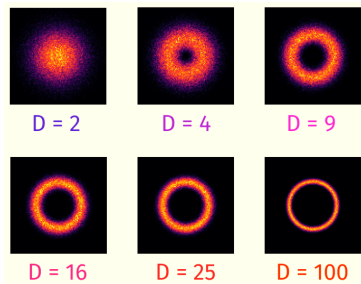


FIGURE 3: Gaussian sampling projections from Jean Feydy course

## STAN a hard but powerful framework

- Good performance but bad documentation
- Autograd and RHMC are not upgraded in python yet.
- Needs to create the cython script by yourself for now.

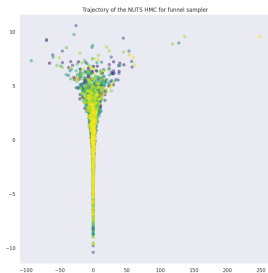


FIGURE 4: NUTS HMC for funnel's distribution



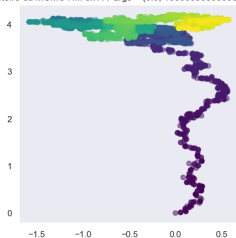
# What is an efficient sampling ?

## Sampling techniques

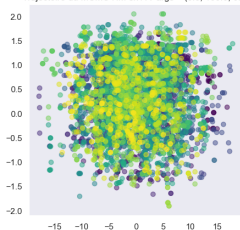
- Use of dependencies : MCMC
- Exploration-exploitation dilemma
  - Exploration to have all the "typical" states
  - Exploitation to obtain the right proportions

## Exploration Exploitation Metropolis Hastings TP4

Trajectoire du MCMC HM ex1 A args = (0.5, 100000000000000.0, 0.001)

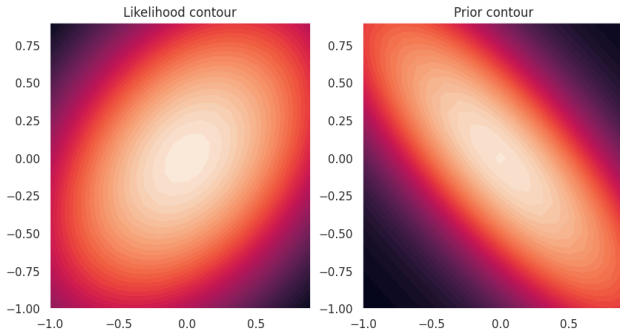


Trajectoire du MCMC HM ex1 A args = (0.5, 100, 0, 1)

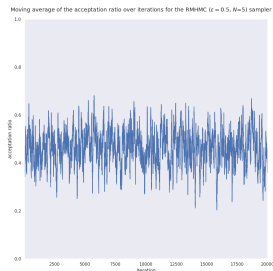
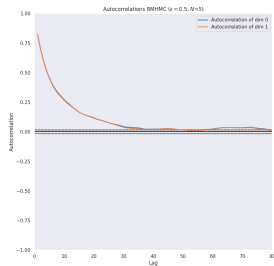
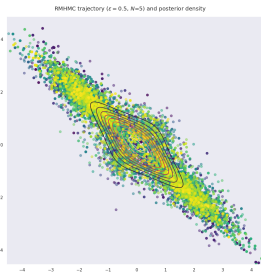
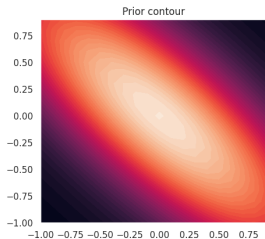
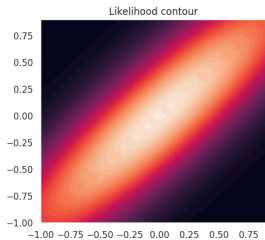


## Toy problem

- $Y|\theta \sim \mathcal{N}(\frac{1}{2}\theta^{\odot 2}, \Sigma_0)$  ( $\odot$ : Hadamard product)
- Prior  $\theta \sim \mathcal{N}(0, \Sigma)$
- Fisher-Rao metric tensor  $G(\theta) = \text{diag}(\theta)\Sigma_0^{-1}\text{diag}(\theta) + \Sigma^{-1}$



# Experiments using our own implementation



# Multimodal distributions for HMC

## HMC

- HMC can be computed but doesn't explore enough.

## HMC 2D Gaussian Mixture and Banana-shape

